

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1-29 (Cancelled)

30. (New) A method for monitoring light paths in an optical network comprising a plurality of optical nodes, each associated with a respective nodal identifier, said optical nodes interconnected by wavelength-multiplexed links and exchanging control signals through a control network, the method comprising the steps of:

modulating an optical signal of each lightpath by an identifying optical signature;

storing at each optical node, for each lightpath planned to traverse said each optical node:

an identifier of a respective optical signature; and

identifiers of adjacent optical nodes designated to be along said each light path;

selecting a target lightpath connecting a source optical node to a destination optical node and a start optical node along said target lightpath, and at a command-line interface communicatively coupled to said start optical node:

determining a target optical signature stored at said start optical node and associated with said target lightpath;

progressively communicating a first message comprising said target optical signature to adjacent optical nodes to determine a first sequence of optical nodes designated to form said target lightpath;

progressively communicating a second message comprising said target optical signature to adjacent optical nodes to determine a second sequence of optical nodes actually receiving said target optical signature; and

comparing said second sequence to said first sequence.

31. (New) The method of claim 30 wherein said first message and said second message are communicated through an external data network.

32. (New) The method of claim 30 wherein the step of comparing comprises a further step of determining congruence of said first sequence and said second sequence to ascertain routing correctness of said target lightpath.

33. (New) The method of claim 30 wherein said start optical node is an intermediate optical node between a source optical node and a destination optical node of said target lightpath, and wherein said first sequence is determined as:

a list of preceding optical nodes, each storing an identifier of said target optical signature, between said start optical node and said source optical node; and

a list of succeeding optical nodes, each storing an identifier of said target optical signature, between said start optical node and said destination optical node.

34. (New) The method of claim 30 wherein said start optical node is an intermediate optical node between a source optical node and a destination optical node of said target lightpath, and wherein said second sequence is determined as:

a list comprising each preceding optical node which detects said target optical signature along said target lightpath between said start optical node and said source optical node; and

a list comprising each succeeding optical node which detects said target optical signature along said target lightpath between said start optical node and said destination optical node.

35. (New) The method of claim 30 wherein the step of progressively communicating said first message further comprises:

responsive to an indication that said start optical node is not said source optical node, identifying at said start node a current node adjacent to said start node towards said source optical node and designated to be on said target lightpath according to provisioning data stored at said start optical node;

sending said first message from said start optical node to said current node;

responsive to an indication that said current node is said source optical node, sending from said current node a completion indication to said start optical node;

responsive to an indication that said current node is not said source optical node:

identifying at said current node a preceding optical node adjacent to said current node and designated to be on said target lightpath according to provisioning data stored at said current node;

sending, from said current node, an identifier of said preceding optical node to said start optical node;

setting said preceding node as a current node; and

returning to the step of sending said first message.

36. (New) The method of claim 35 wherein the step of progressively communicating said first message further comprises:

responsive to an indication that said start optical node is not said destination optical node, identifying at said start node a current node adjacent to said start node towards said destination optical node and designated to be on said target lightpath according to provisioning data stored at said start optical node;

sending said first message from said start optical node to said current node;

responsive to an indication that said current node is said destination optical node, sending from said current node a completion indication to said start optical node;

responsive to an indication that said current node is not said destination optical node:

identifying at said current node a succeeding node adjacent to said current node and designated to be on said target lightpath according to provisioning data stored at said current node;

sending, from said current node, an identifier of said succeeding node to said start optical node;

setting said succeeding node as a current node; and

returning to the step of sending said first message.

37. (New) The method of claim 30 wherein the step of progressively communicating said second message further comprises:

responsive to an indication that said start optical node is not said source optical node, identifying at said start node a current node adjacent to said start node towards said source optical node and designated to be on said target lightpath according to provisioning data stored at said start optical node;

sending said second message from said start optical node to said current node;

responsive to an indication of absence of said target optical signature at said current node, sending from said current node a completion indication to said start optical node;

responsive to an indication that said current node is said source optical node, sending from said current node a completion indication to said start optical node;

responsive to an indication that said current node is not said source optical node:

identifying at said current node a preceding node adjacent to said current node and designated to be on said target lightpath according to provisioning data stored at said current node;

sending, from said current node, an identifier of said preceding node to said start optical node;

setting said preceding node as a current node; and

returning to the step of sending said second message.

38. (New) The method of claim 37 wherein the step of progressively communicating said second message further comprises:

responsive to an indication that said start optical node is not said destination optical node, identifying at said start node a current node adjacent to said start node towards said destination optical node and designated to be on said target lightpath according to provisioning data stored at said start optical node;

sending said second message from said start optical node to said current node;

responsive to an indication of absence of said target optical signature at said current node, sending from said current node a completion indication to said start optical node;

responsive to an indication that said current node is said destination optical node, sending from said current node a completion indication to said start optical node;

responsive to an indication that said current node is not said destination optical node:

identifying at said current node a succeeding node adjacent to said current node and designated to be on said target lightpath according to provisioning data stored at said current node;

sending, from said current node, an identifier of said succeeding node to said start optical node;

setting said succeeding node as a current node; and

returning to the step of sending said second message.

39. (New) The method of claim 30 further comprising:

storing, at said each optical node, identifiers of all adjacent optical nodes of said each optical node;

at a command-line interface communicatively coupled to said start optical node compiling a local-discovery list of identifiers of selected optical nodes initially containing only said start node;

progressively executing, at a current optical node in said local-discovery list, a local-discovery process comprising steps of:

determining identifiers of all adjacent optical nodes to said current optical node;
and

communicating a request to verify detection of said target optical signature to said all adjacent optical nodes, said request including an identifier of said target optical signature;

wherein an adjacent optical node considers only a first reception of said request;

wherein each adjacent optical node which detects said target optical signature sends a respective identifier to said start optical node;

and wherein said start optical node adds said respective identifier to said discovery list.

40. (New) The method of claim 30 further comprising:

storing at said each optical node a set of identifiers of all optical nodes in said optical network;

sending a message from a command-line interface communicatively coupled to said start optical node to each other optical node, said message containing an identifier of said target optical signature and an identifier of said start optical node, said message requesting each individual optical node which detects said target optical signature, to send a response to said target start node said response including an identifier of said each individual optical node; and

including said identifier of said each individual optical node in a global-discovery list for comparison with said first sequence of optical nodes.